NUMERICAL METHOD OF CALCULATE ELECTROMAGNETIC ENERGY IN THE HUMAN HEAD EXPOSED TO AN RF SOURCE

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ABSTRACT

In this paper, I study numerically the behavior of the electric field inside the human head exposed to an RF source (cellular)[1]. For this study, an electromagnetic field coupling was established between an RF source and the head. And to solve the system of equations, a finite element formulation coupled to the boundary integral formulation which is adopted, the results obtained are in the form of arrows with colors in function to the intensity of the electric field \vec{E} . From where we can calculate the intensity of the electric field inside the head, which allows to calculate the SAR, and make a comparison with the SAR measured at the border of head.

Keywords: Electromagnetic Field; Human head; Mobile Phone, Electric; magnetic

INTRODUCTION

The natural electromagnetic field has been in existence for eternity and humans have lived with it, but artificial Electromagnetics have only existed in the last centuries, however there is a question that arises: is the electromagnetic field harmful to human health [2]? The aim of our research here is to answer the question above. In this article we have chosen a part of our research which consists of a numerical study of the intensity and behavior of the electric field inside the human head. In the first case we are going to use as a RF source (the mobile phone) with frequency 1800 MHz, and we suppose that this source is glued to the head of an adult then to the head of a child, and we seek the numerical results without interface between the human head and the RF source. In the second case we put an interface in Silver and we note the numerical results found. In the third case we change the interface material with the use of glass, and we calculate each time the intensity of electric field and the correspondent SAR, and the last step is the comparison between the results.

POSITION OF THE PROBLEM ON THE PHYSICAL PLANE

One of the most important aspects is the problem of diffraction of an electromagnetic wave by an obstacle of any geometric shape. As part of our work, we want to analyze the coupling of an electromagnetic wave with a human head of spherical shape. The sphere is immersed in an RF source (Mobile telephony) [3]. The interaction of the incident wave with the human head introduces the birth of a diffracted wave and a transmitted wave. The dispersion of this electromagnetic energy in the different mediums forming our physical system, directly depends on their electromagnetic characteristics (σ , ε , μ), Their geometric shape, the angle of incidence and the distance *d* between the source and the physical system hence d = 0 (the source is glued to the human head) here.



Figure 1. Physical System

The finite element method (FEM) is one of the most widely used methods for the numerical resolution of Maxwell's equations; its use is based on the transformation of partial differential equations into a system of algebraic equations. The main advantage of this method is the possibility of analyzing problems with complex geometry which may contain heterogeneous materials In general, the finite element resolution is:

- i. The obtaining of the variational formulation of the problem and the definitions of the functional spaces of the admissible solutions.
- The realization of a mesh, corresponding to the discretization of the field of study into ii. simple elements. In which the fields are described in terms of a finite number of degrees of free and basic functions with local support, generally polynomials. We proposed a variational formulation, in which the law of Ampere is written in the weak sense, preserving the electric field like unknown of the problem. This field is calculated in all the computation volume, where the taking into account of the external field is presented by a formulation in integral equation of the border. The use of these formulations is justified in the study of structures where the decomposition of the problem into two parts is more suited to the case treated. In the following, after having given, an integral formulation, we propose a numerical approximation of the solution by the finite element method. The use of variational methods for the resolution of electromagnetic field phenomena requires a numerical approach, posed on a space of finite dimension. For that, we adopted in a numerical model based on the discretization by finite elements in all the field of study. We have presented the mathematical framework in which these equations will be approached numerically, by giving some key properties.

Finite element spaces considered, as well as the matrices resulting from the discretization of variational formulations. This approximate solution allowed us to pass from a system of partial derivative equations to a system of algebraic equations, after the numerical resolution, which includes the calculation of elementary matrices, the corresponding physical quantity (electric field or magnetic field) is known at each point located in our finite element structure considered, as well as the matrices resulting from the discretization of variational formulations.

FORMULATION IN MAGNETIC FIELD $\vec{H}[8]$

Let \vec{H} be a test vector field $\vec{H} \in (\Omega)$, and rot $\vec{H} = 0$ in Ωe for $(\sigma = 0)$. We integrate on R^3 , multiplying by the test function, which give

$$\int_{R^3} i\omega \,\mu \overrightarrow{H}. \,\overrightarrow{H} \,d\Omega \,+\, \int_{R^3} \overrightarrow{H} \,rot \,\overrightarrow{E} \,d\,\Omega = 0 \tag{1}$$

To solve the second integral, we apply some mathematical properties. Which give

$$\int_{R^3} \vec{H} rot \vec{E} d\Omega = \int_{R^3} \vec{E} rot \vec{H} d\Omega = \int_{\Omega} \vec{E} rot \vec{H} d\Omega + \int_{\Omega e} \vec{E} d\Omega$$
(2)

Then (2) becomes

$$\int_{\Omega} i\omega\mu \vec{H}\vec{H} d\Omega + \int_{\Omega} \vec{E}rot\vec{H}d\Omega + \int_{e} i\omega\mu \vec{H}\vec{H} d\Omega = 0$$
(3)
If we replace \vec{E} with $(rot\frac{\vec{H}}{i\omega}\mu)$, we

obtain

$$\int_{\Omega} i\omega\mu \vec{H}.\vec{H}d\Omega + \int_{\Omega} (1/i\omega\varepsilon)rot\vec{H}.\vec{H}rotd\Omega + \int_{\Gamma} (\vec{E}\Lambda\vec{n}).\vec{H}d\Gamma = 0$$
(4)
Formulation in electric field $\vec{E}[9]$

The formulation in an electric field is obtained by writing the Ampère law: $rot\vec{H} = \sigma\vec{E} + i\omega\,\mu\vec{E}$ (5)

We make the dot product with a test function \vec{E}' ($\vec{E}' \in \Omega$) and we integrate in R^3 which gives:

$$\int_{R_3} rot \vec{H}.\vec{E} d\Omega = \int_{R_3} (\sigma + i \omega \mu \varepsilon) \vec{E} \vec{E} d\Omega$$
(6)
With:
 $rot \vec{H} = 0 in and$
 $\vec{E} = 0 in \Omega i.$
To solve the integral
We apply the same properties used previously so we have:

$$\int n. (\vec{H} \Lambda \vec{E}) d\Gamma = 0$$

$$\int_{R^{3}} \vec{E} \ rot \ H \ d\Omega \ - \int_{R^{3}} H \ rot \vec{E'} \ d\Omega = 0$$
Therefore
$$(7)$$

$$\int_{R^3} rot \vec{H} \cdot \vec{E'} d\Omega = \int_{R^3} \vec{H} rot \vec{E'} = \int_{\Omega i} rot \vec{E'} \cdot \vec{H} \, d\Omega + \int_{\Omega e} rot \vec{E'} \cdot \vec{H} \, d\Omega$$
(8)

Multiply by $(-i\omega\mu)$, the formulation in \vec{E} is writen :

$$-\int_{\Omega i} (\sigma \, i\omega\mu\varepsilon)\vec{E}\vec{E}\,d\Omega \int_{\Omega e} \left(\frac{1}{i\omega\mu}\right)rot\vec{E}rot\acute{E}d\Omega + \int_{\Gamma}\vec{E}\,(n\Lambda\,H)\vec{E}\,d\Gamma = 0 \tag{9}$$

$$\int_{\Omega i} rot \vec{E} rot \vec{E} \cdot \vec{E} \cdot d\Omega + \int_{\Omega e} (i\omega\mu\sigma - \omega^2\mu\varepsilon)\vec{E} \cdot \vec{E} \cdot d\Omega + \int_{\Gamma} \vec{E} \cdot (n\Lambda rot \vec{E})d\Gamma = 0$$
(10)

Expression of the electric field in exterior medium We have:

$$\Delta \vec{E} e + k^2 \vec{E} e = \frac{1}{-i\omega\varepsilon_e (k^2 + \overline{grad} \, div) J_s}$$
(11)

with $k^2 = \omega^2 \mu_e \varepsilon_e$ According to equation (11), we have

$$S(x) = -\frac{1}{\omega \varepsilon_e \left(k^2 + \overline{grad}div\right) J(x)}$$
(12)
The amplitude for the function in constant (11) effective to exist a

The application of Green's function in equation (11) allows us to write:

$$\vec{E}e(x) = \int_{\Omega e} G(x, y)S(y)dy$$
(13)

Finally, we will reach our objective, where the global variational formulation of the problem is defined in all the space R^3 , which gives : $A(\vec{E_r}, \vec{E'}) + R(\vec{E_r}, \vec{E'}) = S(\vec{E_s}, \vec{E'})$

$$R(\overrightarrow{E_r}, \overrightarrow{E'}) = -i\omega\mu_e \left(\int_{\Gamma} \frac{k(x)}{2} \overrightarrow{E'}(x) d\Gamma_x + \int_{\Gamma} T\overrightarrow{K}(x) \cdot \overrightarrow{E'}(x) d\Gamma_x\right)$$
(14)

VARIATIONAL DISCRETIZATION OF THE PROBLEM

We recall the variational formulation:

$$A(\overrightarrow{E_r}, \overrightarrow{E'}) + R(\overrightarrow{E_r}, \overrightarrow{E'}) = S(\overrightarrow{E_s}, \overrightarrow{E'})$$

Given that the formulation of the problem is obtained previously, we will thus proceed to the next stage, which consists in the realization of the mesh, by decomposing the variational problem, presented above into elements of edges in an approximate space.

Discretization of the form a $(\mathbf{E}_{r}, \mathbf{E}')[11]$

Then, for each tetrahedron element, the approximate electric field is written:

$$\vec{E'} = \sum_{i=1}^{6} \vec{E_i} Wi$$
(15)

The electric field \overrightarrow{Ei} is a scalar quantity, it represents the degree of freedom per edge *i*.By

taking this interpolation into account, the approximate test field $\vec{E'}$ is therefore written:

$$E' = \sum_{i=1}^{6} Ei Wi$$

We have:

$$a(E_r, E_s) = \int_{\Omega} rot E_r \cdot Rot E' \, d\Omega + \int_{\Omega} (i\omega\mu\sigma - \omega^2\mu\varepsilon)E_r E' d\Omega \tag{16}$$

The approximate form is obtained by decomposing $a(E_r, E')$ into an edge element, which gives:

$$a(E_r, E') = \sum_{tet}^{6} \sum_{i=1}^{6} E_i \int_{\Omega} rot W_i rot W_j d\Omega + (i\omega\mu\sigma - \omega^2\mu\varepsilon) \sum_{tet}^{6} \sum_{i=1}^{6} E_i \int_{\Omega} W_i W_j d\Omega$$
(17)

The form given by (4) can be written in the following matrix form:

$$a(E_r, E') = E\{[T1] + (i\omega\mu\sigma - \omega^2\mu\varepsilon)[T2]\}$$
(18)

Where \vec{E} is the unknown vector.

$$\vec{E} = [E_1, E_2, \dots, E_N]^T$$

With T1 and T2 are time-independent matrices whose elementary terms are given by:

$$[T1]_{ij} = \int_{\Omega} rot W_i rot W_j d\Omega = 4 \int_{\Omega} (\nabla \lambda_{ai} \lambda_{bi}) (\nabla \lambda_{bi} \lambda_{bj}) d\Omega$$
(19)

$$[T2]ij = \int_{\Omega} W_i W_j d\Omega = \int_{\Omega} (\lambda_{ai} \nabla \lambda_{bi} - \lambda_{bi} \nabla \lambda_{ai}) \cdot (\lambda_{aj} \nabla \lambda_{bj} - \lambda_{bj} \nabla \lambda_{aj})$$
(20)

Construction and calculation of the second member (S)

The term linked to the source is given by

$$S\left(\overrightarrow{E_{s}},\overrightarrow{E'}\right) = -\int_{\Omega} rot \overrightarrow{E_{s}} rot \overrightarrow{E'} d\Omega - \int_{\Omega} (i\omega\mu\sigma - \omega^{2}\mu\varepsilon)\overrightarrow{E_{s}} - \int_{\Gamma} \overrightarrow{E'} \vec{n} \Lambda rot \overrightarrow{E_{s}}) d\Gamma$$

The approximate form of S is written:

$$S(\vec{E_{s}}, \vec{E'}) = \sum_{tet}^{6} \sum_{i=1}^{6} E_{si} \int_{\Omega} rot W_{i} rot W_{j} d\Omega$$
$$- (i\omega\mu\sigma - \omega^{2}\mu\varepsilon) \sum_{tet}^{6} \sum_{i=1}^{6} E_{si} \int_{\Omega} W_{i} W_{j} d\Omega + \sum_{tet}^{3} \sum_{i=1}^{3} E_{si} \int_{\Gamma} (n\Lambda rot W_{i}) W_{j} d\Gamma (21)$$
The elementary matrices are defined by

)

$$[S_{1}]_{ij} = \int_{\Omega} rot W_{i} rot W_{j} d\Omega = 4 \int_{\Omega} (\nabla \lambda_{ai} \nabla \lambda_{bi}) (\lambda_{aj} \nabla \lambda_{bj}) d\Omega$$
$$[S_{2}]_{ij} = \int_{\Omega} W_{i} W_{j} d\Omega = \int_{\Omega} (\lambda_{ai} \nabla \lambda_{bi} - \lambda_{bi} \nabla \lambda_{ai}) (\lambda_{aj} \nabla \lambda_{bj} - \lambda_{bj} \nabla \lambda_{aj}) d\Omega$$

$$[F]_{ij} = \int_{\Gamma} (n \operatorname{Arot} W_i) W_j d\Gamma = 2 \int_{\Gamma} [n \operatorname{A} (\nabla \lambda_{ai} \nabla \lambda_{bi})] (\lambda_{aj} \nabla \lambda_{bj} - \lambda_{bj} \nabla \lambda_{aj}) d\Gamma$$
(22)

So the second member S is given as follows

 $S(E_s, E') = E_s\{[S_1] - (i\omega\mu\sigma - \omega^2\mu\varepsilon)[S_2] + [F]\}$

Breakdown of the edge term [24]

The calculation of the edge term is established in (14)

$$R(\overrightarrow{E_r}, \overrightarrow{E'}) = -i\omega\mu_e \left(\int_{\Gamma} \frac{k(x)}{2} \overrightarrow{E'}(x) d\Gamma_x + \int_{\Gamma} T\overrightarrow{K}(x) \overrightarrow{E'}(x) d\Gamma_x\right)$$
(23)
Or

$$T \vec{K}(x) = \vec{n} \wedge \int_{\Gamma} \overline{grad} y G(x, y) \wedge \vec{K}(y) d\Gamma_{y}$$

The discretization of $R(\vec{E}_r, \vec{E}')$, involves a test field, such as: $\vec{E}'(x) = W_j(x)Wj(x)$

Using the fictitious current relation K the term

 $T \vec{K}(x)$ is approached as

$$[T K(x)E'(x)] = \sum_{j}^{Na} \sum_{i}^{Ne} \{ \iint_{\Gamma\Gamma} \frac{[n \Lambda((x-y)\Lambda W_{i}(y)]W_{j}(x)}{|x-y|^{3}} d\Gamma_{x} d\Gamma_{y} \}$$
(25)
$$(Q_{i}^{-1}B)_{ij} E_{j}$$

The system of equations given above can be written in the following matrix form

$$(M)_{ji} = \iint_{\Gamma\Gamma} \frac{\{n \Lambda[(x-y)\Lambda W_i(y)]\}W_j(x)}{|x-y|^3} d\Gamma_x d\Gamma_y$$
So, the relation (25) is written:
$$(26)$$

So, the relation (25) is written:

$$[TK(x), E'(x)] = \sum_{j=1}^{Na} \left\{ \sum_{i=1}^{Ne} (M)_{ji} (Q_i^{-1}B)_{ij} \right\} E_j$$
(27)

We have directly defined the first term of R(Er, E'')

$$\frac{1}{2}[TK(x), E'(x)] = \frac{1}{2} \sum_{i}^{Ne} P_i \int_{\Gamma} W_j(x) W_i(x) d\Gamma_x$$
(28)

From where

$$\frac{1}{2}[TK(x), E'(x)] = \frac{1}{2} \sum_{j}^{Na} \left\{ \sum_{i}^{Ne} \left(B^{-t} \right)_{ji} ji(Q_i^{-1}B)_{ij} \right\}$$
(29)

 B° is the transpose of the matrix B

Finally, the global matrix of the edge term, noted R_m in edge variables, is written as

$$R_m = \sum_{i} [\frac{1}{2}B^{t} + M]_{ji} (Q_i^{-1}B)_{ij}$$

Or

(24)

$$R_m = [\frac{1}{2}B^{t} + M]Q_i^{-1}B$$

Taking into account these elementary matrices (27), (28) and (29), the global matrix system, denoted MAT, is therefore written:

$$MAT = E\{[T_1] + (i\omega\mu\sigma - \omega^2\mu\varepsilon)[T_2] + R_m\} = S$$

After the imposition of the appropriate boundary conditions, the results are obtained by solving for a given excitation frequency, a matrix equation of the type[A] x = b, where[A] is a hollow matrix with complex coefficients.

NUMERICAL IMPLENTATION

Our model's simulation is presented in the form of a human head and an interface which presents two mediums. The exterior is an interface and the interior is the human brain of an adult and a child. We have considered the two homogeneous, isotropic, and dispersive mediums. We have chosen frequencies of the electromagnetic source, f = 1800MHz, for 4G standard

Electrical characteristics of the two mediums for (f = 1800 MHz)[25]

Concerning the ELM source, this is characterized by

-frequency; f = 1800MHz; -Current: $Js = 200 \ A/m^2$. Brain characteristics (interior medium) -Electrical permittivity: $\varepsilon_{ric} = 43,22$ -Electrical conductivity: $\sigma_{ic} = 1,29 \ S/m_{.}$ -Permeability: $\mu = 1$ Electrical characteristics of the silver interface - Electrical conductivity $\sigma_{e1} = 6,25 \ 10^7 \ \frac{s}{m}$ -Electrical permittivity: $\varepsilon_{re1} = 2,5$. -Permeability : $\mu = 1$

The meshing of the domain of study

The structure mesh was obtained with the meshing tool CELLULAIR 003 characterized by a tetrahedral discretization data on the mesh realize. Our meshing tool allowed us to read the mesh, as follows:

C:\MAHREZ\Debug\CELLULAIRE003 (3).exe		
/		A
PEAU = 3.9894227E-02 **** LECTURE DU MAILLAGE TERMINEE** MAILLE MOVENNE = 0.643E-01	***	
NB DE SOMMETS INTERNES :	5961	
NB DE SOMMETS FRONTALIERS :	1454	
NB D'ARETES INTERNES	36454	
NB D'HREIES FRUNIHLIERES	4J56 2004	
NB DE TETRAEDDEG	2704	
NB DE TETRHEDRES	31744	
RAYON MAX DES SPHERES INSCRITES DS	LES TETRAS 0.0118730	

(a)

	1 X*X8 high read * 1-1 Y 1 1 1 1 1 1
C:\MAHREZ\Debug\CELLULAIRE003 (3).exe"	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	0.253 0.634 -2.30 6.43 -4.60 -5.30 -6.12 -3.60 5.01 -2.34 2.29 3.50 2.97
<pre>(E-ROTH)/(E+ROTH)= NaN , (H-ROTE)/(H+ROTE)= F I N N O R M A L E D U C O D E * NOMBRE DE MOTS DEMANDES: 25000000 * NOMBRE DE MOTS UTILISES: 10665686 TEMPS CPU POUR CELFEW : 59.85156 Press any key to continue</pre>	NaN

(b)





Figure 3. Mesh of our model (human head)

Numerical results obtained from an RF source glued to the human head

We performed numerical tests, using our calculation code that we developed:

-The first test: the electromagnetic source glued to the human head, and we had a frequency

f = 1800 MHz, with the variation of the electrical characteristics of the exterior medium of our model which is obtained from the setting up of our interface by different materials or we used for this test, Silver($\mu_{e1}, \varepsilon_{e1}, \sigma_{e1}$),

After each test we obtained numerical results in the form of a cartography, which represents the behavior and the intensity with the colors of the electric field inside the human head.

Numerical results without interface

The source, it is characterized by: frequency

f = 1800MHz, current Js = 200 A / m2, the distance between the source and the human head d = 0.005 m (the source glued to the human head)



Figure 4. Electric field intensity \vec{E} (mV / m), Human Head without interface **The results with a Silver interface**

The source, it is characterized by: f = 1800MHz current $Js = 200 A / m^2$, the distance between the source and the human head d = 0.005 m (the source glued to the head)



Figure 5. Electric field intensity \vec{E} (mV/m) Human Head with Silver interface

FORMULATION AND CALCLATE OF SAR

The formulation of specific absorption rate [28]:

$$SAR = \frac{\sigma E^2}{m_d}$$

Incident power density = $\frac{E^2}{377}$

Where, σ = Conductivity of Material, E = Electric Field, m_d = Mass Density

The SAR measured (SAR) = 6.78 W/kg [29]

(30)

From the numerical results presented in figures (4) and (5) we calculated the SAR, without interface and with silver interface, where is shown in the following table.

Distance (mm)	SAR (W/kg)without interface	SAR (W/kg) with silver interface
10	6.78	6.78
20	8.43	6.93
30	9.56	5.56
40	8.12	3.12
50	7.12	2.12
60	2.32	1.32
70	1.45	0.45
80	0.56	0.36
90	0.39	0.34
100	0.34	0.30
110	0.28	0.28

Table 1. The SAR inside human head, without interface and with Silver interface



Figure 6. The SAR inside human head, with a silver interface and without interface

INTERPRETATION AND DISCUSSION

Using our numerical method, we can calculate the electric field \vec{E} at each point inside the human head, which is practically non- measurable. We have also noticed that for an electromagnetic source glued to the human head, and of frequency, (f = 1800), the electric field \vec{E} varies according to the distance d inside the human head, which implies the variation of the DAS [equation (30)], For our tests, with a model without interface and another with an interface in Silver, we have the numerical results indicated in figures (4) and (5) from which we withdraw the values of the electric field \vec{E} inside the human head, which makes it possible to calculate the SAR inside it, hence the SAR values are shown in TableI1. And shown graphically in Fig. 6. For a model with interfaces and without interface. We noticed

that the SAR had an increase or a peak just after the entry of the electric field inside the human head Fig. 5. After the SAR decreased in function of the distance (d) in the human head, and for a Silver interface we notice the disappearance of the peak.

For giving to the explanation of this peak we use equation (30), hence the SAR and as a function of σ (the electrical conductivity of the medium) [26].

And therefore the exterior medium is the air which conductivity σ which is very small compared to the interior medium, which is the brain. Which explains the increase in the value of the SAR, and also explains the elimination of the peak if the interface and in Silver, hence the value of the electrical conductivity σ , and greater than that of the interior medium which a brain.

We therefore observed that the SAR measured on the outside and smaller than that on the inside just after the entry of the electric field. And for the correction we used interface in Mittal of silver to have the same SAR measured at the exterior [29] of the human head and that interior (brain).

CONCLUSION

This part of our work is a subject of a contribution to search for the problems of the interaction of the electromagnetic fields with the human head, we have defined the physical system and posed the problem, from Maxwell's equations in a harmonic regime, a synthesis of various variational formulations was done to solve the problem numerically. For the implementation of the proposed formulations, we used the finite element method. By adopting digital finite element resolution coupled with the integral boundary method, we finally had a digital result in the form of a map containing the colored arrows that represented the electric field and its intensity inside the human head. The results obtained for a frequency f = 1800 MHz and a source stuck to the head. We used the behavior of the electric field to calculate its intensity and the SAR for certain points inside the human head. Finally, we compared the results obtained for the SAR calculated inside the human head and the SAR measured at the limit. And we found that the SAR inside underwent an increase just at the entry of the electric field at the Inside the human head, this increase which is in the form of a peak and for the correction we have proposed a Silver interface which gave us good results.

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